

## ***EUMETSAT - Copernicus Sentinel-3 SLSTR L2 NRT FRP Product Data Format Specification***

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## Change Record

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V1.0	18/03/2020		Initial
V1.A	30/03/2020		Modification report / file name IPF Code version non indicated anymore (for internal document management tool convenience). Acronym list updated. Updated product size, and FRP data content.
V1.B	28/09/2020		Update format table, and removal common parts to all product structure / manifest (available in other common documents).

**\*DCR = Document Change Request**

## Table of Contents

<b>1</b>	<b>INTRODUCTION.....</b>	<b>5</b>
1.1	Scope .....	5
1.2	Applicable Documents.....	5
1.3	Reference Documents.....	5
1.4	Terminology .....	5
1.5	Document Structure .....	6
<b>2</b>	<b>NRT S3 SLSTR L2 FRP PRODUCT DESCRIPTION.....</b>	<b>7</b>
2.1	General product structure.....	7
2.2	NRT S3 SLSTR L2 FRP product: SL_2_FRP____.....	7
2.2.1	Product summary .....	7
2.2.2	Manifest file .....	8
2.2.3	Measurement data file – FRP_in.nc.....	8
2.2.4	Annotation data files .....	11
2.2.4.1	Global flags data file - flags_in.nc.....	11
2.2.4.2	Full resolution geodetic coordinate annotation data file - geodetic_in.nc .....	14
2.2.4.3	Solar and satellite geometry annotation data file - geometry_tx.nc.....	15
<b>3</b>	<b>XML SCHEMA.....</b>	<b>17</b>
<b>4</b>	<b>NRT S3 SLSTR L2 FRP PRODUCT SIZE.....</b>	<b>18</b>

Table of Figures	Figure 1: S3 Product package.....	7
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## Table of Tables

Table 1:	NRT SLSTR L2 FRP product composition .....	7
Table 2:	NRT SLSTR L2 FRP – FRP_in.nc description .....	8
Table 3:	FRP summary flag word values.....	10
Table 4:	FRP classification byte values .....	11
Table 5:	Global flags flag_in.nc description .....	11
Table 6:	Cloud word definitions .....	13
Table 7:	Bayesian cloud word definitions .....	13
Table 8:	Pointing word definitions .....	13
Table 9:	Confidence word definitions .....	13
Table 10:	Full resolution geodetic coordinate annotation data file description .....	14
Table 11:	Solar and satellite geometry annotation data file description.....	15
Table 12:	NRT SLSTR L2 FRP product size per 5-min granule .....	18

## 1 INTRODUCTION

### 1.1 Scope

This document describes the format of the Near Real Time (NRT) Level 2 (L2) Fire Radiative Power (FRP) product generated from the Copernicus Sentinel-3 (S3) Sea and Land Surface Temperature Radiometer (SLSTR) by EUMETSAT.

### 1.2 Applicable Documents

	<b>Document Title</b>	<b>Reference</b>
AD-1	Sentinel 3 PDGS File Naming Convention	EUM/LEO-SEN3/SPE/10/0070 GMES-S3GS-EOPG-TN-09-0009, Issue 1.3, 07/11/2012
AD-2	Product Data Format Specification - Product Structures	S3IPF.PDS.002, Issue 1.6, 10/02/2015
AD-3	XML Schemas.zip – Zip file containing all the schemas used to represent the metadata	S3IPF.PDS.009, i2r5 – 26/03/2015
AD-4	EUMETSAT - Copernicus Sentinel-3 SLSTR L2 NRT FRP Auxiliary Data Format Specification	EUM/SEN3/DOC/20/1169484, v1.B, 28/09/2020.

### 1.3 Reference Documents

	<b>Document Title</b>	<b>Reference</b>
RD-1	Product Data Format Specification - Level 0	S3IPF PDS 001 - Product Data Format Specification - Level 0
RD-2	Product Data Format Specification – SLSTR Level 1 and 2	S3IPF PDS 005 - Product Data Format Specification - SLSTR
RD-3	Active Fire : Fire Detection And Fire Radiative Power Assessment – S3 SLSTR L2 FRP ATBD	S3-L2-SD-03-T04-KCL-ATBD_FIREPRODUCT, v4.3, 31/10/2019.

### 1.4 Terminology

AD	Applicable Document
ADF	Auxiliary Data File
ATBD	Algorithm Theoretical Basis Document

BT	Brightness Temperature
CFI	Customer Furnished Items
ESA	European Space Agency
EUMETSAT	European Organisation for the Exploitation of Meteorological Satellites
FRP	Fire Radiative Power
IPF	Instrument Processing Facility
L1	Level 1
L2	Level 2
MWIR	Medium Wave InfraRed
NRT	Near Real Time
PDGS	Payload Data Ground Segment
RSP	Remote Sensing and Products division
RD	Reference Document
S3	Sentinel-3
SLSTR	Sea and Land Surface Temperature Radiometer
SWIR	Short Wave-InfraRed
TIR	Thermal InfraRed

## **1.5 Document Structure**

This document is structured as follow:

- NRT S3 SLSTR L2 FRP product description in Section 2;
- Manifest file description in Section 1;
- XML schema in Section 3;
- NRT S3 SLSTR L2 FRP product size in Section 4.

## 2 NRT S3 SLSTR L2 FRP PRODUCT DESCRIPTION

### 2.1 General product structure

The format of all Sentinel 3 products is described in [AD-2]. The Product Package is illustrated in Figure 1.

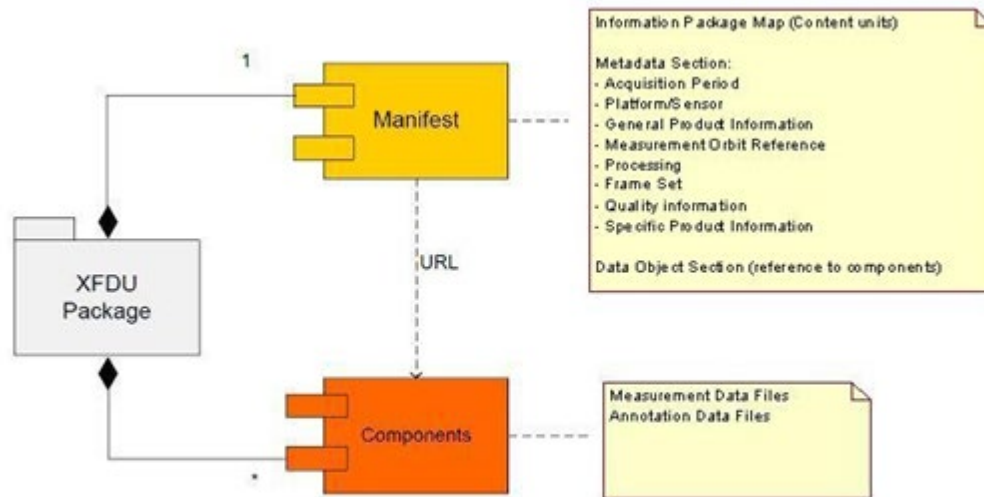


Figure 1: S3 Product package

### 2.2 NRT S3 SLSTR L2 FRP product: SL\_2\_FRP\_\_

This product contains the list of parameters for each detected hot-spot, including its FRP value Medium Wave InfraRed (MWIR) and/or Short-Wave InfraRed (SWIR).

#### 2.2.1 Product summary

The NRT S3 SLSTR L2 FRP product contains one measurement and three annotation data files.

Table 1: NRT SLSTR L2 FRP product composition

Product Package Type <b>SL_2_FRP</b>		Description Fire Detection and Fire Radiative Power Parameters			
Product Level	Diss. Timeliness	Product Category	Application Domain		Spatial Resolution
2	NRT	Available to the user	LND		1 Km
Product Dissemination Unit Stripe		Number of Package components	Number of Measurement Files	Number of Annotation Data Files	Number of Representation Information Files
		14 <sup>1</sup>	1	13	0
Product Package Structure					

<sup>1</sup> Number of Package components includes the manifest and the OLCR Report.

**EUMETSAT - Copernicus Sentinel-3 SLSTR L2 NRT FRP Product Data  
Format Specification**

Manifest file	
File name	Composition
xfdmanifest.xml	XML fields
Measurement Data files (see section Error! Reference source not found. for more details)	
File name	Composition
FRP_in.nc	i, j, time, latitude, longitude, FRP_SWIR, FRP_MWIR, FLAG_SWIR_SAA, FRP_uncertainty_SWIR, FRP_uncertainty_MWIR, TCWV, transmittance_SWIR, transmittance_MWIR, transmittance_SWIR, IFOV_area, glint_angle, confidence, classification, window_size, flags, S7_Fire_pixel_radiance, F1_Fire_pixel_radiance, used_channel, Radiance_window, n_window, n_water, n_cloud, n_SWIR_fire.
Annotation Data files	
File name	Composition
flags_in.nc	cloud_in, bayes_in, pointing_in, confidence_in, cloud_orphan_in, bayes_orphan_in, pointing_orphan_in, confidence_orphan_in
geodetic_in.nc	latitude_in, longitude_in, elevation_in, latitude_orphan_in, longitude_orphan_in, elevation_orphan_in
geometry_tn.nc	solar_zenith_tn, solar_azimuth_tn, solar_path_tn, sat_zenith_tn, sat_azimuth_tn, sat_path_tn

### 2.2.2 Manifest file

The structure of the manifest file is described in [AD-2].

### 2.2.3 Measurement data file – FRP\_in.nc

The measurement data file contains all key scientific result associated with the NRT FRP processor, especially FRP (from MWIR and/SWIR), FRP uncertainty FRP (from MWIR and/SWIR) and other supporting fields associated with each individual detected hot-spot reported at 1 km resolution on the SLSTR S7 image grid. Furthermore, for each original pixel in the S7 image grid, a series of flags is provided associated with each detection test result (see ATBD in [RD-3]). This allows further analyses related to potential omitted fires or false alarms and identify the reason (*i.e.* the detection test responsible of this phenomenon).

**Table 2: NRT SLSTR L2 FRP – FRP\_in.nc description**

Element name	Description	Range or value	T	D
fires	Fire list array size			
rows	Along track grid size			
columns	Across track grid size			
<common global attributes>	Common global attributes			
i	Fire pixel across-track image grid index		i32	fires
j	Fire pixel along-track image grid index		i16	fires
time	Time		i64	fires
standard_name	CF standard name	time		1
units	UDUNITS unit name	Microseconds since 2000-01-01T00:00:00		
latitude	Latitude	[-90; 90]	f64	fires



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Format Specification**

Element name	Description	Range or value	T	D
standard_name	CF standard name	latitude		1
units	UDUNITS unit name	degrees_north		1
<b>longitude</b>	<b>Longitude</b>	<b>[-180; 180]</b>	<b>f64</b>	<b>fires</b>
standard_name	CF standard name	longitude		1
units	UDUNITS unit name	degrees_east		1
<b>FRP_MWIR</b>	<b>Fire radiative power computed from MWIR channels (S7 and F1)</b>		<b>f64</b>	<b>fires</b>
units	UDUNITS unit name	MW		1
<b>FRP_uncertainty_MWIR</b>	<b>Fire radiative power total uncertainty computed from MWIR channels (S7 and F1)</b>		<b>f64</b>	<b>fires</b>
units	UDUNITS unit name	MW		1
<b>transmittance_MWIR</b>	<b>Transmittance of path to fire computed from MWIR channels (S7 and F1)</b>		<b>f64</b>	<b>fires</b>
<b>FRP_SWIR</b>	<b>Fire radiative power computed from SWIR channels (S5 and S6)</b>		<b>f64</b>	<b>fires</b>
units	UDUNITS unit name	MW		1
<b>FRP_uncertainty_SWIR</b>	<b>Fire radiative power total uncertainty computed from SWIR channels (S5 and S6)</b>		<b>f64</b>	<b>fires</b>
units	UDUNITS unit name	MW		1
<b>FLAG_SWIR_SAA</b>	<b>Flag South Atlantic Anomaly (SAA) suspected from SWIR channels (S5 and S6)</b>		<b>i32</b>	<b>fires</b>
<b>transmittance_SWIR</b>	<b>Transmittance of path to fire computed from SWIR channels (S5 and S6)</b>		<b>f64</b>	<b>fires</b>
<b>confidence</b>	<b>Fire detection confidence</b>	<b>[0 ; 100]</b>	<b>f64</b>	<b>fires</b>
<b>classification</b>	<b>Hotspot classification code</b>	<b>See Table 4</b>	<b>u8</b>	<b>fires</b>
flag_values	Flag values	See Table 4		1
flag_masks	Flag masks	See Table 4		1
flag_meanings	Flag descriptions	See Table 4		1
<b>S7_Fire_pixel_radiance</b>	<b>Fire pixel radiance computed from S7 brightness Temperature</b>	<b>[-32767, 32767]</b>	<b>i16</b>	<b>fires</b>
standard_name	CF standard name	toa_radiance		1
scale_factor	Scaling factor used in decoding packed data	0.01		1
units	UDUNITS unit name	mW.m-2.sr-1.nm-1		1
<b>F1_Fire_pixel_radiance</b>	<b>Fire pixel radiance computed from F1 brightness Temperature</b>	<b>[-32767, 32767]</b>	<b>i16</b>	<b>fires</b>
standard_name	CF standard name	toa_radiance		1
scale_factor	Scaling factor used in decoding packed data	0.01		1
units	UDUNITS unit name	mW.m-2.sr-1.nm-1		1

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Format Specification**

Element name	Description	Range or value	T	D
<b>used_channel</b>	<b>Boolean flag indicating which channel was used in the FRP calculation, with 0 referring to S7 channel and 1 to F1 channel</b>	[0,1]		fires
<b>Radiance_window</b>	<b>Average background window radiance used in the FRP equation. This radiance is associated with the channel defined by the used_channel parameter</b>	[-32767, 32767]	i16	fires
standard_name	CF standard name	toa_radiance		1
scale_factor	Scaling factor used in decoding packed data	0.01		1
units	UDUNITS unit name	mW.m-2.sr-1.nm-1		1
<b>Glint_angle</b>	<b>Angle between SLSTR viewing direction and the direction of the sun rays specifically reflected from the horizontal surface</b>		f64	fires
units	UDUNITS unit name	degrees		1
<b>IFOV_area</b>	<b>Projected area of detector IFOV on surface</b>		f64	fires
units	UDUNITS unit name	m2		1
<b>TCWV</b>	<b>Total column water vapour above fire</b>		f64	fires
standard_name	CF standard name	atmosphere_water_vapor_content		1
source	Data source	ECMWF files		1
units	UDUNITS unit name	kg m-2		1
<b>n_window</b>	<b>Background window size</b>		i16	fires
<b>n_water</b>	<b>Number of water pixels in background window</b>		i16	fires
<b>n_cloud</b>	<b>Number of cloudy pixels in background window</b>		i16	fires
<b>n_SWIR_fire</b>	<b>Number of fires detected on the 500m grid using the S6 absolute test. This number is only relevant for oceanic or daytime land detected fires. The others cases are associated with a "-1" value</b>	[0,4]	u16	fires
_FillValue	Value indicating missing data	-1		
<b>flags</b>	<b>Fire test summary flags</b>	See Table 3	i16	rows columns
flag_values	Flag values	See Table 3		1
flag_meanings	Flag descriptions	See Table 3		1
flag_maskss	Flag masks	See Table 3		1

**Table 3: FRP summary flag word values**

Bit number	Value	Text Code	Description
0	1	exception	L1b pixel radiance exception
1	1	l1b_water	L1b water surface classification
2	1	frp_water	Water detected by FRP tests
3	1	l1b_cloud	Cloud detected by L1b tests
4	1	bayesian_cloud	Cloud detected by Bayesian tests

**EUMETSAT - Copernicus Sentinel-3 SLSTR L2 NRT FRP Product Data  
Format Specification**

5	1	frp_cloud	Cloud detected by FRP tests
6	0	night	Pixel is in day or night
	1	day	
7	1	sun_glint	Sun glint
8	1	spectral_filter	Potential fire identified by spectral test
9	1	spatial_filter	Potential fire identified by spatial test
10	1	absolute_threshold	Fire identified by absolute threshold test
11	1	background_characterisation	Potential fire successful background characterisation
12	1	contextual_threshold	Potential fire confirmed by contextual threshold test
13	1	desert_boundary	Potential fire rejected by desert boundary test
14	0	No Fire	Normal fire have BT <500K
	1	Saturated fire	Saturation fire have BT >500K
15	0	Low confidence fire	Low confidence (0-50%)
	1	High confidence fire	High confidence (50-100%)
16	1	abs_bckg_invalid	if raised, Fire detected by absolute test but associated with unvalid background
17	1	saturated_area	<b>if raised, pixel is located on a saturated area (i.e the percentage of S7-saturated pixel are higher than a certain threshold) and “classic” FRP detection cannot be processed over this pixel</b>
18	1	cloud_edge	if raised, this potential fire pixel has been discarded due to neighboring cloudy pixels
19	1	land-water_edge	if raised, this potential fire pixel has been discarded due to too many neighbors with inconsistent surface classification.

**Table 4FRP classification byte values**

Bit number	Text Code	Description
0	vegetation_fire	If raised, suspected vegetation fire
1	onshore_gas_flare	if raised, suspected onshore gas flare
2	offshore_gas_flare	if raised, Suspected offshore gas flare
3	volcanic	if raised, Suspected volcanic hotspot
4	industrial	if raised, Suspected industrial hotspot
5	spare	spare
6	spare	spare
7	spare	spare

## 2.2.4 Annotation data files

### 2.2.4.1 Global flags data file - flags\_in.nc

The global flags annotation data file contains the product quality flags that are applicable across all measurement datasets sharing the same view and detector geometry. In the SLSTR FRP product, the global flags are applicable to the 1 km nadir view thermal channels.

**Table 5: Global flags flag\_in.nc description**

Element name	Description	Range or value	T	D
rows	Along track grid size			
columns	Across track grid size			
orphan_pixels	Maximum Number of un-regridded (orphaned) pixels on each image line			
<common global attributes>	Common global attributes			
Probability_cloud_single_i<v>	Probability of cloud in pixel (single view)	[-100, 100]	i16	rows columns
_FillValue	Value indicating missing data	-32768		1

**EUMETSAT - Copernicus Sentinel-3 SLSTR L2 NRT FRP Product Data  
Format Specification**

Element name	Description	Range or value	T	D
scale_factor	Scaling factor used in decoding packed data	0.005		1
add_offset	Offset used to in decoding packed data	0.5		1
comment	comment	Probability of cloud in pixel as estimated by Bayesian Cloud detection on a single view		1
<b>Probability_cloud_dual_i&lt;v&gt;</b>	<b>Probability of cloud in pixel (dual view)</b>	<b>[-100, 100]</b>	<b>i16</b>	<b>rows columns</b>
_FillValue	Value indicating missing data	-32768		1
scale_factor	Scaling factor used in decoding packed data	0.005		1
add_offset	Offset used to in decoding packed data	0.5		1
comment	comment	Probability of cloud in pixel as estimated by Bayesian Cloud detection on both views		1
<b>cloud_&lt;g&gt;&lt;v&gt;</b>	<b>Global cloud flags (basic SLSTR cloud tests)</b>		<b>u16</b>	<b>rows columns</b>
flag_masks	Masks for each flag bit	See Table 6		1
flag_meanings	Text descriptions for each flag bit	See Table 6		1
<b>bayes_&lt;g&gt;&lt;v&gt;</b>	<b>Bayesian cloud flags</b>	<b>[0b; 100b]</b>	<b>u8</b>	<b>rows columns</b>
flag_masks	Masks for each flag bit	See Table 7		1
flag_meanings	Text descriptions for each flag bit	See Table 7		1
<b>pointing_&lt;g&gt;&lt;v&gt;</b>	<b>Global pointing flags</b>		<b>u8</b>	<b>rows columns</b>
flag_masks	Masks for each flag bit	See Table 8		1
flag_meanings	Text descriptions for each flag bit	See Table 8		1
<b>confidence_&lt;g&gt;&lt;v&gt;</b>	<b>Global confidence flags</b>		<b>u16</b>	<b>rows columns</b>
flag_masks	Masks for each flag bit	See Table 9		1
flag_meanings	Text descriptions for each flag bit	See Table 9		1
<b>cloud_orphan_&lt;g&gt;&lt;v&gt;</b>	<b>Orphan pixel global cloud flags</b>		<b>u16</b>	<b>rows orphan_pixels</b>
flag_masks	Masks for each flag bit	See Table 6		1
flag_meanings	Text descriptions for each flag bit	See Table 6		1
<b>bayes_orphan_&lt;g&gt;&lt;v&gt;</b>	<b>Orphan pixel Bayesian cloud flags</b>		<b>u8</b>	<b>rows orphan_pixels</b>
flag_masks	Masks for each flag bit	See Table 7		1
flag_meanings	Text descriptions for each flag bit	See Table 7		1
<b>pointing_orphan_&lt;g&gt;&lt;v&gt;</b>	<b>Orphan pixel global pointing flags</b>		<b>u8</b>	<b>rows orphan_pixels</b>
flag_masks	Masks for each flag bit	See Table 8		1

**EUMETSAT - Copernicus Sentinel-3 SLSTR L2 NRT FRP Product Data  
 Format Specification**

Element name	Description	Range or value	T	D
flag_meanings	Text descriptions for each flag bit	See Table 8		1
<b>confidence_orphan_&lt;g&gt;&lt;v&gt;</b>	<b>Orphan pixel global confidence flags</b>		<b>u16</b>	<b>rows orphan_pixels</b>
flag_masks	Masks for each flag bit	See Table 9		1
flag_meanings	Text descriptions for each flag bit	See Table 9		1

**Table 6: Cloud word definitions**

Bit	Text code	Meaning if set	Comment
0		Visible channels cloud test	Day time only
1		1.37µm threshold test	Day time only
2		1.6µm small-scale histogram test	Day time only
3		1.6µm large-scale histogram test	Day time only
4		2.25µm small-scale histogram test	Day time only
5		2.25µm large-scale histogram test	Day time only
6		11µm spatial coherence test	
7		12µm gross cloud test	
8	thin_cirrus	11µm/12µm thin cirrus test	
9		3.7µm/12µm medium/high level test	
10	fog_low_stratus	11µm/3.7µm fog/low stratus test	
11		11µm/12µm view difference test	Uses both views
12		3.7µm/11µm view difference test	Uses both views
13	thermal_histogram	11µm/12µm thermal histogram test	
14		spare	
15		spare	

**Table 7: Bayesian cloud word definitions**

Bit	Text code	Meaning if set	Comment
0		Single view low probability threshold	Climate-quality clearing
1		Single view moderate probability threshold	Operational-quality clearing
2		Dual view low probability threshold	Climate-quality clearing
3		Dual view moderate probability threshold	Operational-quality clearing
4		spare	
5		spare	
6		spare	
7		spare	

**Table 8: Pointing word definitions**

0	FlipMirrorAbsoluteError	flip mirror absolute error exceeds threshold	
1	FlipMirrorIntegratedError	flip mirror integrated error exceeds threshold	
2	FlipMirrorRMSError	flip mirror RMS error exceeds threshold	
3	ScanMirrorAbsoluteError	scan mirror absolute error exceeds threshold	
4	ScanMirrorIntegratedError	scan mirror integrated error exceeds threshold	
5	ScanMirrorRMSError	scan mirror RMS error exceeds threshold	
6	ScanTimeError	Scan time is inconsistent with scan count sequence	
7	Platform_Mode	platform mode	0 if nominal, else 1

**Table 9: Confidence word definitions**

## EUMETSAT - Copernicus Sentinel-3 SLSTR L2 NRT FRP Product Data Format Specification

Bit	Text code	Meaning if set	Comment
0	coastline	coastline in field of view	
1	ocean	ocean in field of view	
2	tidal	tidal zone in field of view	
3	land	land in field of view	
4	inland_water	inland water in field of view	
5	unfilled	unfilled pixel (1 if this pixel is never tested or filled)	
6		(spare)	
7		(spare)	
8	cosmetic	cosmetic fill pixel	
9	duplicate	Pixel has a duplicate	
10	day	pixel in daylight	
11	twilight	pixel in twilight	
12	sun_glint	sun glint in pixel	
13	snow	snow	
14	summary_cloud	summary cloud test	
15	summary_pointing	summary pointing	

### 2.2.4.2 Full resolution geodetic coordinate annotation data file - geodetic\_in.nc

The geodetic coordinates dataset contains the ortho-geolocated geodetic coordinates, in latitude and longitude, and the surface elevation of the centre of each field of view on the earth's surface, determined from a digital elevation model. The dataset is generated in the image frame. The dataset is encoded in NetCDF 4. In the NRT SLSTR L2 FRP product, the given file is the one dedicated to the 1 km nadir view S7 thermal channel.

**Table 10: Full resolution geodetic coordinate annotation data file description**

Element name	Description	Range or value	T	D
rows	Along track grid size			
columns	Across track grid size			
orphan_pixels	Maximum number of un-regridded (orphaned) pixels on each image line			
<common global attributes>	Common global attributes			
latitude_<g><v>	Latitude of detector FOV centre on the earth's surface	[-90; 90]	i32	rows columns
standard_name	CF standard name	latitude		1
units	UDUNITS unit name	degrees_north		1
scale_factor	Scaling factor used in decoding packed data	1e-6		1
add_offset	Offset used to in decoding packed data	0		1
_FillValue	Value indicating missing data	-2147483648		1
longitude_<g><v>	Longitude of detector FOV centre on the earth's surface	[-180; 180]	i32	rows columns
standard_name	CF standard name	longitude		1
units	UDUNITS unit name	degrees_east		1
scale_factor	Scaling factor used in decoding packed data	1e-6		1

**EUMETSAT - Copernicus Sentinel-3 SLSTR L2 NRT FRP Product Data  
Format Specification**

Element name	Description	Range or value	T	D
add_offset	Offset used to in decoding packed data	0		1
_FillValue	Value indicating missing data	-2147483648		1
<b>elevation_&lt;g&gt;&lt;v&gt;</b>	<b>Surface elevation of detector FOV centre above reference ellipsoid</b>	<b>[-450; 9000]</b>	<b>i16</b>	<b>rows columns</b>
standard_name	CF standard name	surface_altitude		1
units	UDUNITS unit name	m		1
scale_factor	Scaling factor used in decoding packed data	0.1		1
add_offset	Offset used to in decoding packed data	0		1
_FillValue	Value indicating missing data	-32768		1
<b>latitude_orphan_&lt;g&gt;&lt;v&gt;</b>	<b>Latitude of detector FOV centre on the earth's surface associated with un-regridded pixels</b>	<b>[-90; 90]</b>	<b>i32</b>	<b>rows orphan_pixels</b>
standard_name	CF standard name	latitude		1
units	UDUNITS unit name	degrees_north		1
scale_factor	Scaling factor used in decoding packed data	1e-6		1
add_offset	Offset used to in decoding packed data	0		1
_FillValue	Value indicating missing data	-2147483648		1
<b>longitude_orphan_&lt;g&gt;&lt;v&gt;</b>	<b>Longitude of detector FOV centre on the earth's surface associated with un-regridded pixels</b>	<b>[-180; 180]</b>	<b>i32</b>	<b>rows orphan_pixels</b>
standard_name	CF standard name	longitude		1
units	UDUNITS unit name	degrees_east		1
scale_factor	Scaling factor used in decoding packed data	1e-6		1
add_offset	Offset used to in decoding packed data	0		1
_FillValue	Value indicating missing data	-2147483648		1
<b>elevation_orphan_&lt;g&gt;&lt;v&gt;</b>	<b>Surface elevation of detector FOV centre above reference ellipsoid associated with un-regridded pixels</b>	<b>[-450; 9000]</b>	<b>i16</b>	<b>rows orphan_pixels</b>
standard_name	CF standard name	surface_altitude		1
units	UDUNITS unit name	m		1
scale_factor	Scaling factor used in decoding packed data	0.1		1
add_offset	Offset used to in decoding packed data	0		1
_FillValue	Value indicating missing data	-32768		1

### 2.2.4.3 Solar and satellite geometry annotation data file - geometry\_tx.nc

The Solar and satellite geometry annotation data file contains the solar and satellite azimuth and zenith angles at earth's surface and the corresponding distances to the surface, on a tie point grid. The resolution of this grid is 1 km on along-track direction and 16 km on across-track one. Only the nadir view file is included in the FRP product.

**Table 11: Solar and satellite geometry annotation data file description.**

**EUMETSAT - Copernicus Sentinel-3 SLSTR L2 NRT FRP Product Data  
 Format Specification**

Element name	Description	Range or value	T	D
<b>rows</b>	<b>Along track grid size</b>			
<b>columns</b>	<b>Across track grid size</b>			
<common global attributes>	Common global attributes			
<b>solar_zenith_&lt;g&gt;&lt;v&gt;</b>	<b>Solar zenith angle</b>		<b>f32</b>	<b>rows columns</b>
standard_name	CF standard name	"solar_zenith_angle"		1
units	UDUNITS unit name	"degrees"		1
<b>solar_azimuth_&lt;g&gt;&lt;v&gt;</b>	<b>Solar azimuth angle</b>		<b>f32</b>	<b>rows columns</b>
standard_name	CF standard name	"solar_azimuth_angle"		1
units	UDUNITS unit name	"degrees"		1
<b>solar_path_&lt;g&gt;&lt;v&gt;</b>	<b>Distance from sun to surface</b>		<b>f32</b>	<b>rows columns</b>
units	UDUNITS unit name	"m"		1
<b>sat_zenith_&lt;g&gt;&lt;v&gt;</b>	<b>Satellite zenith angle</b>		<b>f32</b>	<b>rows columns</b>
standard_name	CF standard name	"sat_zenith_angle"		1
units	UDUNITS unit name	"degrees"		1
<b>sat_azimuth_&lt;g&gt;&lt;v&gt;</b>	<b>Satellite azimuth angle</b>		<b>f32</b>	<b>rows columns</b>
standard_name	CF standard name	"sat_azimuth_angle"		1
units	UDUNITS unit name	"degrees"		1
<b>sat_path_&lt;g&gt;&lt;v&gt;</b>	<b>Distance from satellite to surface</b>		<b>f32</b>	<b>rows columns</b>
units	UDUNITS unit name	"m"		1



### **3 XML SCHEMA**

The xml schemas used to generate the product manifest are provided as separate files [AD-4].

#### 4 NRT S3 SLSTR L2 FRP PRODUCT SIZE

Table 12 lists the size computation per product file produced over a 5-min granule. A file compression is applied (ratio of 4) on FRP\_in.nc.

The overall product size over 1 full day (24h) is about 24 Gbytes. Note that the number of detected files has a very minor impact on product size as the largest part is due to annotations files. Only the size and the content of FRP\_in.nc file is impacted by the number of fires. The size of annotations files remains constant as they are associated with the whole SLSTR image and not only the detected fires.

The following is noted by EUMETSAT and worth being highlighted to the users:

- The product format has evolved, based on in-house EUMETSAT modifications and developments. Notably, the number of annotation data files has been drastically reduced as well as the overall data volume (about a factor of 2).
- Nevertheless, the format will be further optimized in the next upgrade, in the near future. Notably, it is expected that only key attributes included in the annotation files will be transferred to the FRP measurement file.
- Hence, it is expected that the overall volume of the NRT FRP product will be further reduced soon. EUMETSAT will communicate about this activity in the near future.

**Table 12: NRT SLSTR L2 FRP product size per 5-min granule**

Element name	Description	Size in Mbytes
xfdmanifest.xml	Sentinel-SAFE product manifest	
FRP_in.nc	1km fire radiative power measurement dataset	~0.8
flags_in.nc	Nadir 1km global flags dataset	31
geodetic_in.nc	Nadir 1km geodetic coordinates dataset	40
geometry_tn.nc	16km nadir solar and satellite geometry dataset	15
<b>Total</b>		<b>~87</b>