



Science and Technology Institute

GLM Single Group Flash Analysis

6 December 2022

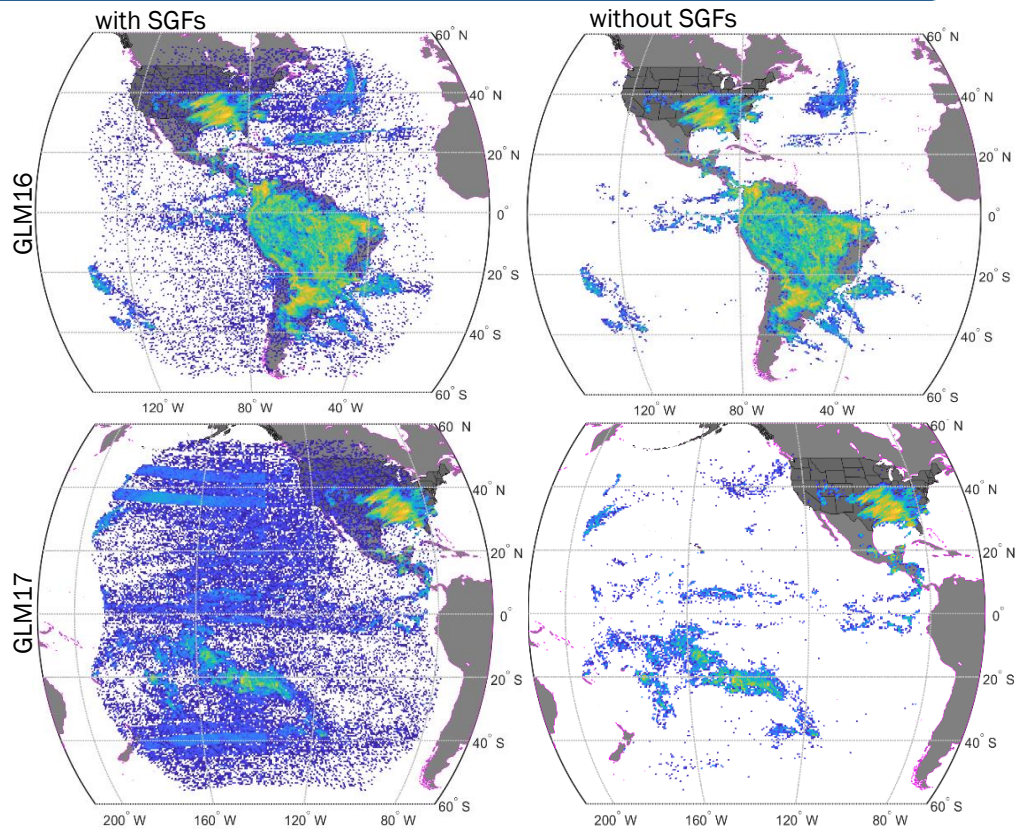
Douglas Mach

Senior Scientist, USRA/STI

Introduction

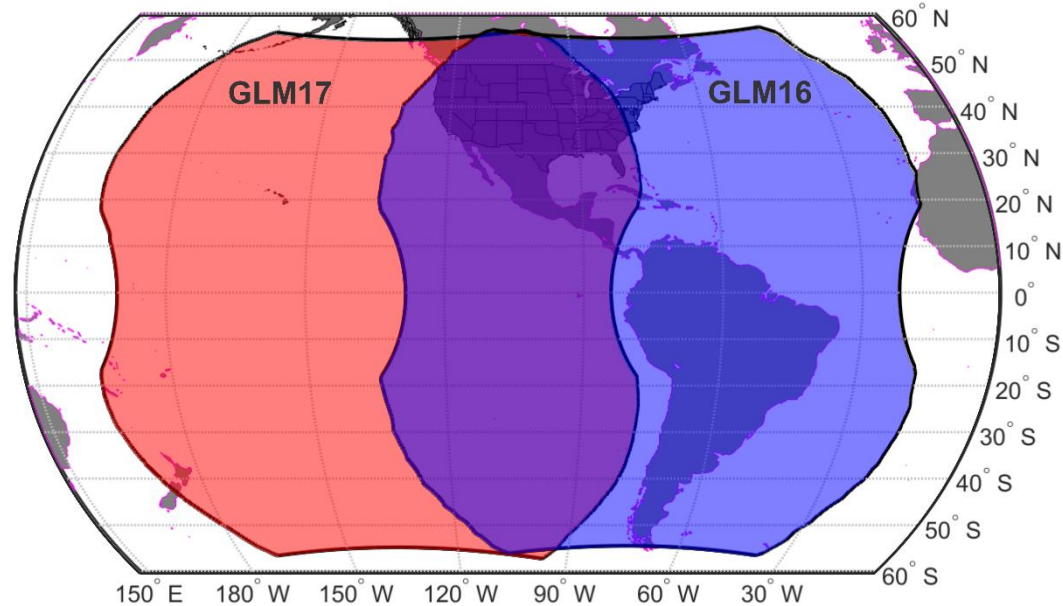
The current operational GLM Lightning Cluster Filter Algorithm (LCFA) removes all flashes with only a single group

- Example GLM data with and without SGFs
- Acronyms
 - Single Group Flashes (SGFs)
 - Multiple Group Flashes (MGFs)
 - Operational algorithm
 - GLM on GOES-16 (GLM16)
 - GLM on GOES-17 (GLM17)



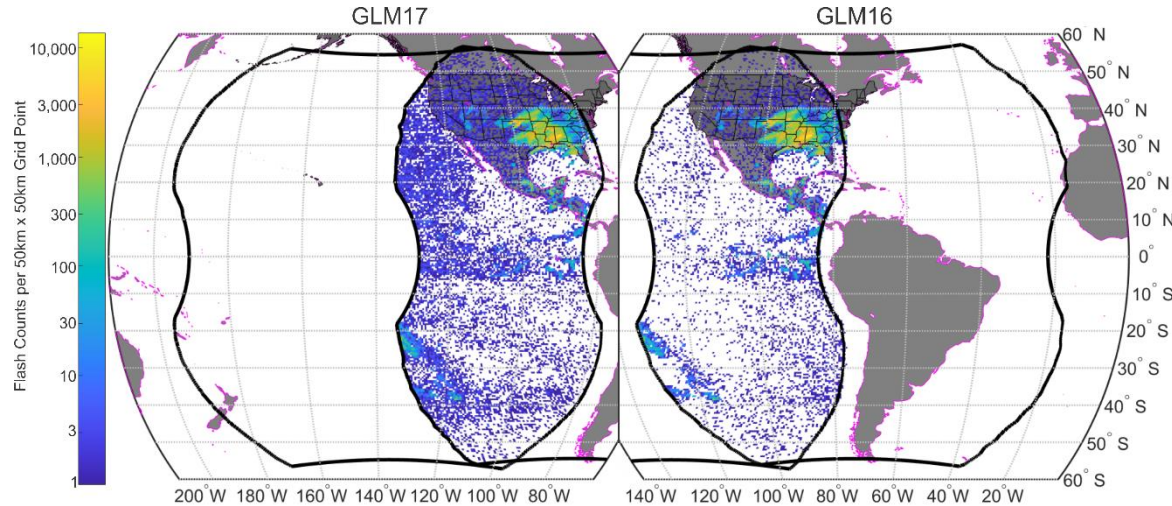
Introduction (cont)

- How much “real lightning” is removed by the SGF filter?
 - How much GLM lightning consists of only a single group?
- Protocol
 - Create a “ground truth” dataset
 - Common flashes between GLM16 and GLM17
 - Compare ground truth to GLM16 and GLM17 SGFs and MGFs
 - Determine fraction (and locations) of SGFs and MGFs that are in/not in the ground truth dataset



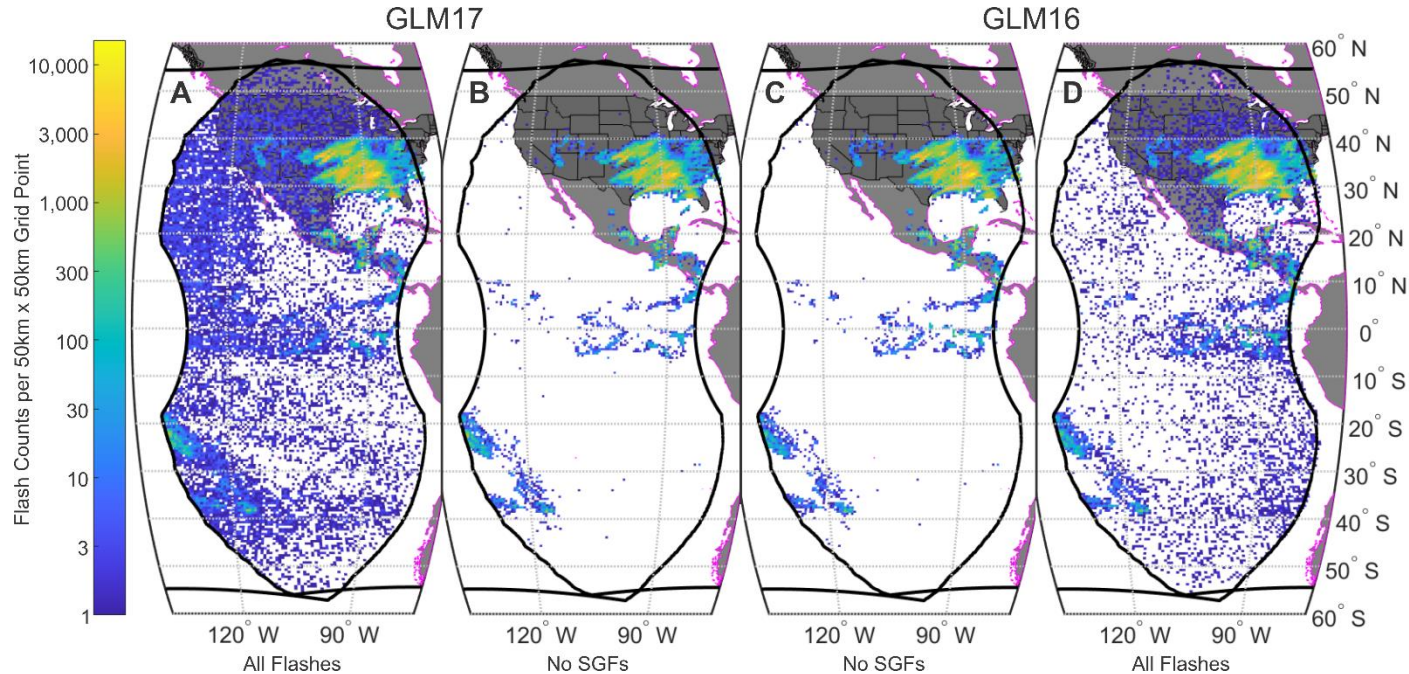
Study Dataset

- L1b events (not filtered for SGFs)
 - 00:00Z 16 March 2021 to 00:00Z 19 March 2021
 - Clustered into L2 flashes (without the Operational Algorithm group and flash count and temporal limits)
- GLM16 and GLM17 flashes in overlap region
- 740248 GLM16 flashes in overlap region (including SGFs)
- 623084 GLM17 flashes in overlap region (including SGFs)



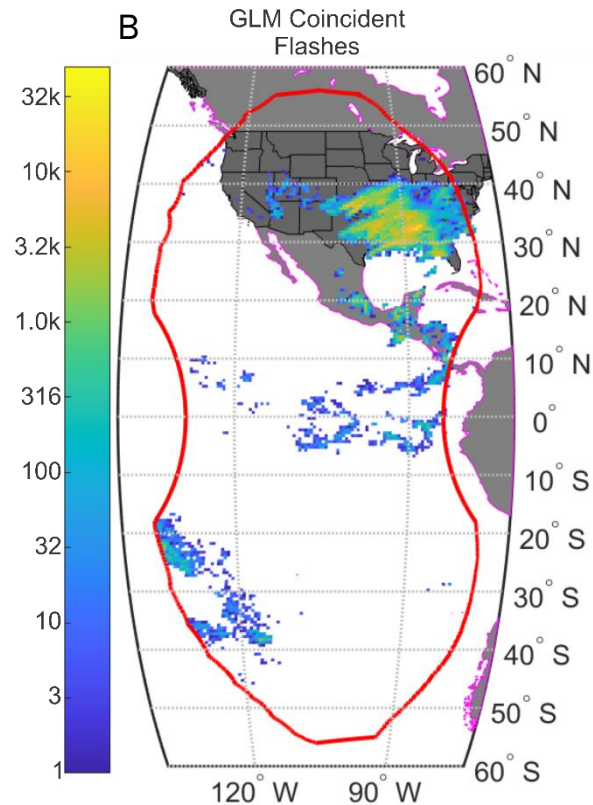
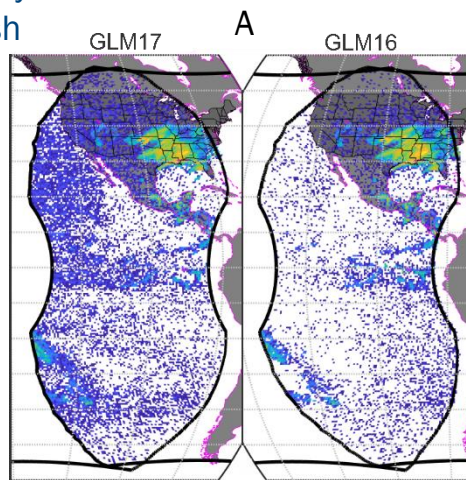
Operational Algorithm (w/SGF filter) vs. All Flashes (no SGF filter)

- GLM16
 - 661699 MGFs (C)
 - 740248 total flashes (D)
 - 11% SGFs
- GLM17
 - 520407 MGFs (B)
 - 623084 total flashes (A)
 - 16% SGFs
- SGFs small fraction of data (~10-15%)
 - Plots including SGFs look “noisier”
 - Most “noise” grid boxes have 1-2 SGFs



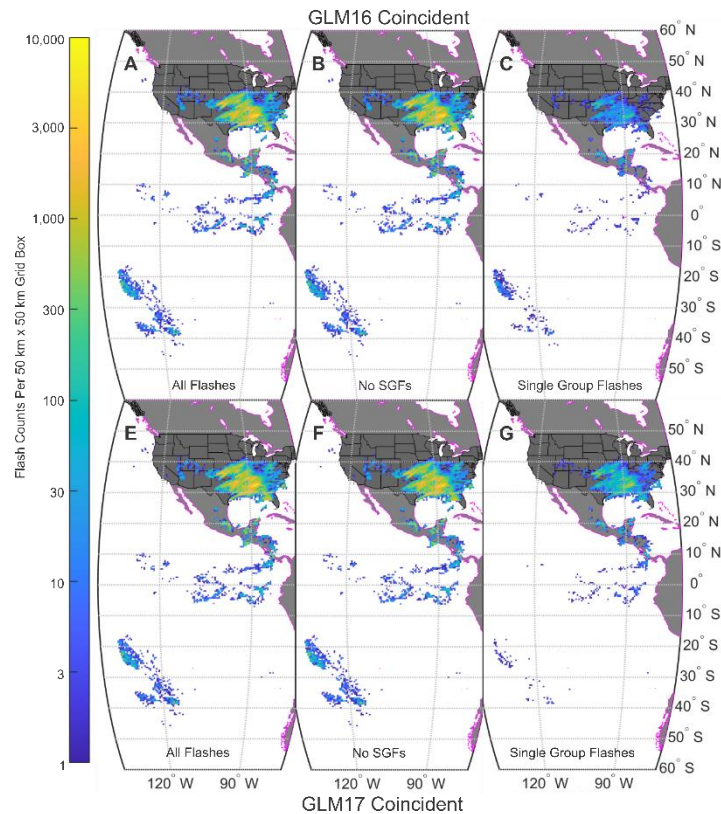
Common Flash Determination

- Spatial limit in this analysis is set to 20 km
 - Based on parallax measurements in Mach (2021)
- Temporal limit is set to 0.5 s
 - GLM flash times are more accurate than 0.5s
 - The larger time window allows for the possibility of one GLM missing the initial groups of a flash
- Utilizing the parameters above...
 - 558490 GLM16 common flashes
 - 586423 GLM17 common flashes
 - Not always one-to-one GLM16 to GLM17 flashes



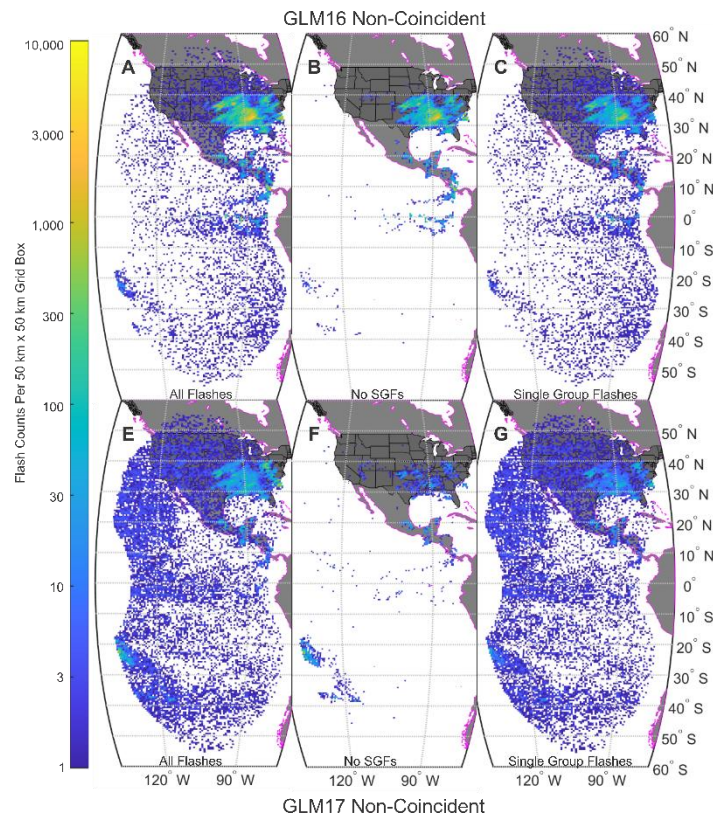
Results: Coincident Flashes

	Coincident Flashes		
	All	Multiple Group Flashes	Single Group Flashes
GLM16	558490 (75%)	537218 (73%)	21272 (3%)
GLM17	586423 (94%)	508454 (82%)	77969 (13%)



Results: Non-Coincident Flashes

	Non-Coincident Flashes		
	All	Multiple Group Flashes	Single Group Flashes
GLM16	181758 (25%)	125582 (17%)	56176 (8%)
GLM17	36661 (6%)	11953 (2%)	24708 (4%)

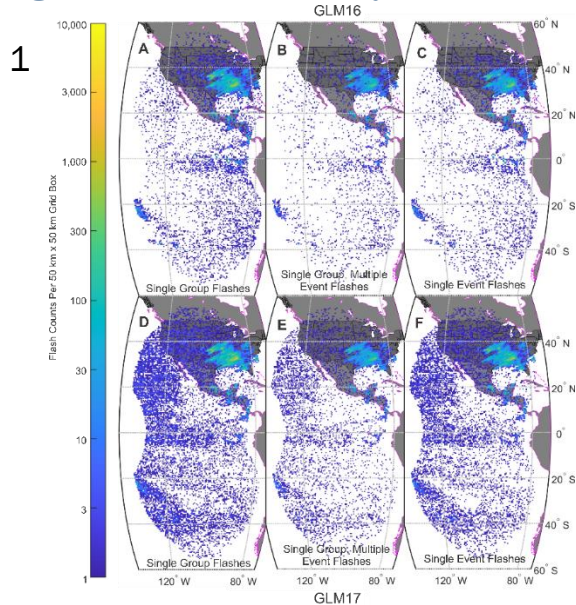


Conclusions

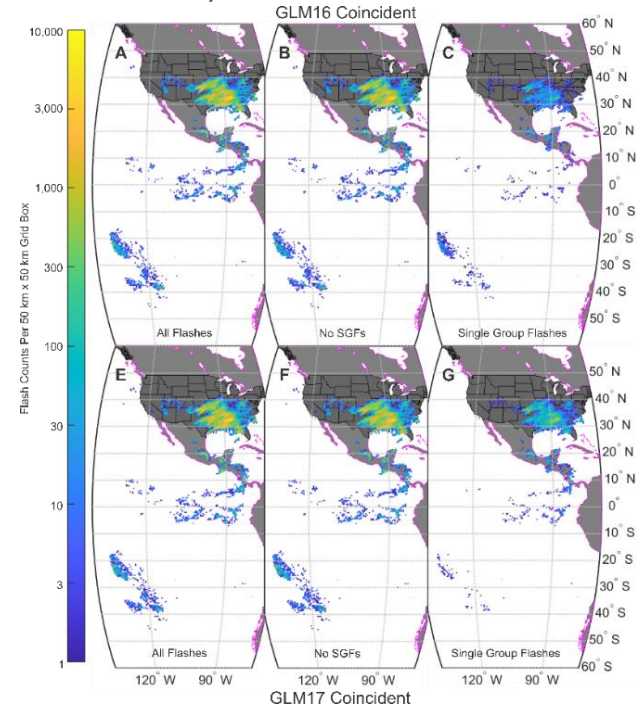
- 11-16% of flashes that pass the L1b filters are SGFs
- 75-94% of flashes that pass the L1b filters are coincident between GLM16 and GLM17
- Most of the flashes (73-82%) that are coincident are MGFs
- A small fraction (3-13%) of the coincident flashes are SGFs
- Non-coincident flashes tend to have a more random distribution
- Coincident flashes tend to cluster with other coincident flashes
- The Single Group Flash eliminates most non-coincident flashes (successful filter)
- There is room for improvement

Future Work

- Some SGFs are coincident between the two GLMs
- Simply keeping the SGFs (or just eliminating Single Event Flashes) NOT the solution
- Coincident SGFs cluster with the coincident MGFs
- Working on “Innocence by Association” filter for SGFs



2



QUESTIONS?

Extra Information: Coincidence Determination

- Two general ways to determine temporal and spatial separation
 - Difference between flash start times ($\Delta t_1, \Delta t_3$)
 - Time gap between flashes ($\Delta t_2, \Delta t_4$)
 - Distance between flash centroids distances ($\Delta d_1, \Delta d_3$)
 - Minimum distance between events in the two flashes ($\Delta d_2, \Delta d_4$)
- Time gap between flashes ($\Delta t_2, \Delta t_4$)
 - Note that for the coincidence determination, Δt_4 will be considered 0 s
- Minimum distance between events in the two flashes ($\Delta d_2, \Delta d_4$)
 - Note that for the coincidence determination, Δd_4 will be considered 0 km

